

A new generation of hydrounit monitors*

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ABSTRACT

Monitoring of a hydro unit can be performed by a simple system and still be very efficient if a multidimensional approach is applied to signal sensing and to signal and data processing. The advantages of this concept are low costs and easier maintenance, which make it suitable for all units and plants and not only for the large ones. The output of such a system and some typical applications are illustrated.

Introduction

If the system used to monitor hydro unit operation is separated from the system used to control it, the monitoring system can be rather simple. By organizing the monitoring in a multidimensional way, the functionality of such a simple system can surpass a system based on complex hardware and a costly collection of specialized software subsystems, which is a common configuration offered on the world market. The term *multidimensional* is used to describe a monitoring algorithm based on the full usage of observable data on all the dimensions of monitored processes. This implies suitable sampling of all the quantities in space, time, rotor instantaneous position, frequency, and the domain of state variables; true multidimensional processing of such data; using direct and hidden inter-relationships among the data; and optimizing the monitoring algorithm based on secondary data yielded by such a procedure.

The multidimensional concept was initially introduced for the diagnostics and monitoring of cavitation [1]. First, turbines with a high number of runner blades were considered. The concept was later broadened to the case of a low number of runner blades as well [2]. This approach was based on a detailed study of sensors and signal and data processing problems [3]. Several examples of successful application have been presented [1, 2, 4, and 5].

In this paper, the concept of general multidimensional monitors is illustrated. Such simple and inexpensive but effective systems might well be the next generation of hydropower unit monitors, offering a solution well-suited for plants and units of all sizes.

Implementation

The best strategy of devising a monitoring system for a unit under consideration is:

- perform first a diagnostic test on it;
- use the operators' insights and the diagnostic test results to define the list of quantities to be monitored; optimize the selection, number, and location of sensors;
- adapt the multidimensional algorithm to the unit.

By following this strategy, rather than installing a pre-defined "one size fits all" system, the monitoring system can be cost-effectively tailored to the unit-specific or plant-specific issues. The last step of matching the multidimensional algorithm to the particularities and peculiarities

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of the unit is crucial. This ensures high sensitivity for detecting deterioration effects and improves monitoring reliability.

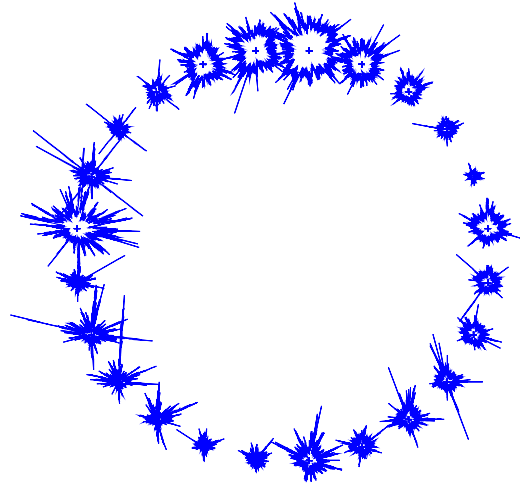
Whatever the result of such an optimization, the monitoring system can be quite simple. It consists of sensors, a small industrial computer with an analog-to-digital conversion card, and multidimensional software. No additional analog units are needed with suitable selection of the A-D card. This reduction in hardware reduces costs, simplifies maintenance, and permits easy reconfiguration of the system.

Sensing

Problems with sensing dynamic signals are illustrated here using an example of cavitation diagnostics. The figure shows the results from a cavitation test performed on a bulb unit, and similar results are exhibited by Francis and Kaplan units. The sensors in 24 positions around the turbine runner yielded 24 curves as shown. These curves describe the dependence of cavitation noise power (radial co-ordinate) on the instantaneous angular position of the runner (angular co-ordinate).

The peaky structure of the curves reflects the changes in cavitation conditions that the runner blades experience while passing through the wake fields of guide vanes. Each peak is related to a single blade-vane pair, and

analysis of such curves yields data on cavitation qualities of individual runner blades and data on the influence individual guide vanes have on cavitation.



The curves in the figure differ significantly, both in form and in mean value. Thus, by taking into account only one or few sensors, incorrect estimates of the cavitation intensity related to pairs might be obtained, and the same holds for the mean intensity estimates. Therefore, in order to get a true characterization of cavitation in a turbine, either in the form of detailed data or in the form of data on the total cavitation in the turbine, one must use a sufficiently high number of sensors suitably distributed over the turbine. Cavitation monitors that spare on sensors may yield non-representative results.

Processing

The situation with respect to spatial sensing, illustrated here by cavitation, is encountered while monitoring other dynamic quantities as well. The same holds true for the algorithms used to process signals and acquired data. A particular **analysis-synthesis** procedure is needed in order to make the results interpretable and reliable. Using the cavitation example above, this procedure can be presented as follows: (1) decompose the peaky structures of strongly mixed contributions from different blade-vane pairs; (2) distinguish between different cavitation mechanisms; and then (3) synthesize quantities such as the intensity of a particular mechanism on a particular blade behind a particular vane.

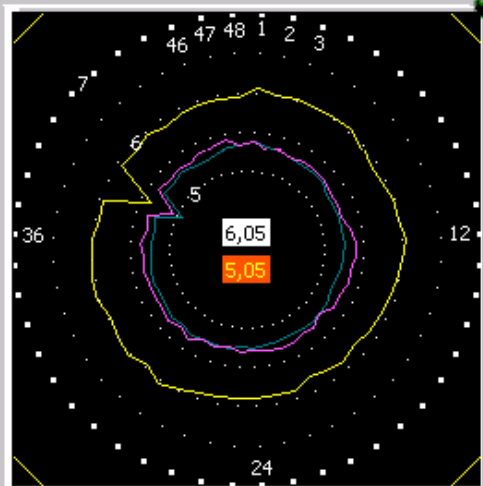
Data presentation

In several figures that follow the typical output of a monitor is illustrated. The design bringing all important data in the basic window is adopted, and for details, one clicks further.

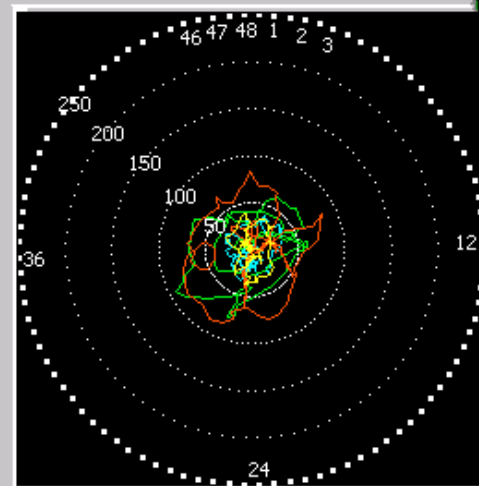
HED Ag A

Režim	Temperatura
GVS m	blaz gen
149,25	46,0
DVS m	blaz aks uz
129,65	53,5
Pad ul r m	blaz ak niz
0,36	68,0
OPK %	blaz turb
70,4	46,2
ORK %	ulje gen
69,6	39,3
Qag m3/s	ulje aks
198,3	44,9
Srad MW	ulje turb
35,9	38,7
Sjal MVar	ulje g spr
4,7	40,7
Eta %	sred stat
89,7	72,9
SradD MW	
0,5	
SjaD MVar	
-0,8	
QagD m3/s	
0,9	

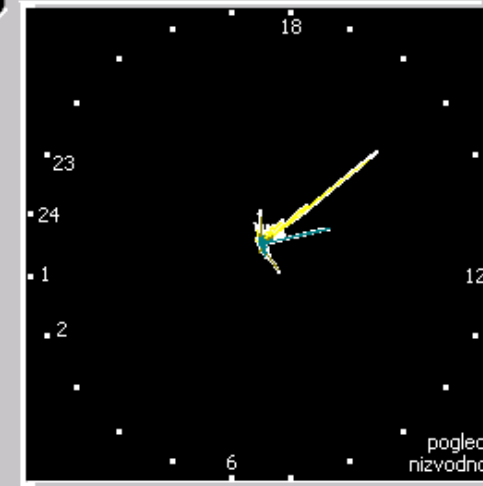
Zračni raspored (mm) i magnetski tok (T)



Vibracije vratila (µm)



Intenzitet kavitacije

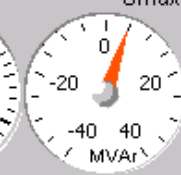
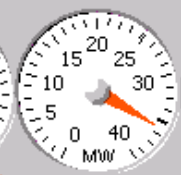
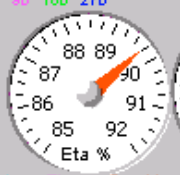


Ekscentricitet uzvod nizvod 0 90 180 270

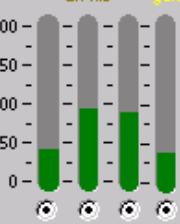
iznos (µm): 0 8
na polu: 0,0 25,6

tur ak niz ak uz gen

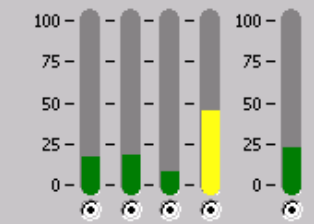
Kav uk sred % GVS m DVS m OPK % ORK % Eta % SradA MW



Smax µm tur ak niz ak uz gen



Lopata 1 2 3 4 Ukupno

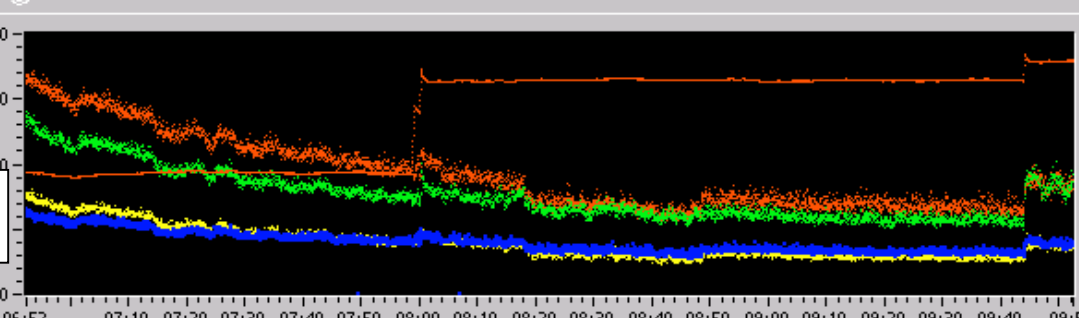


Razlučivanje grubo fino



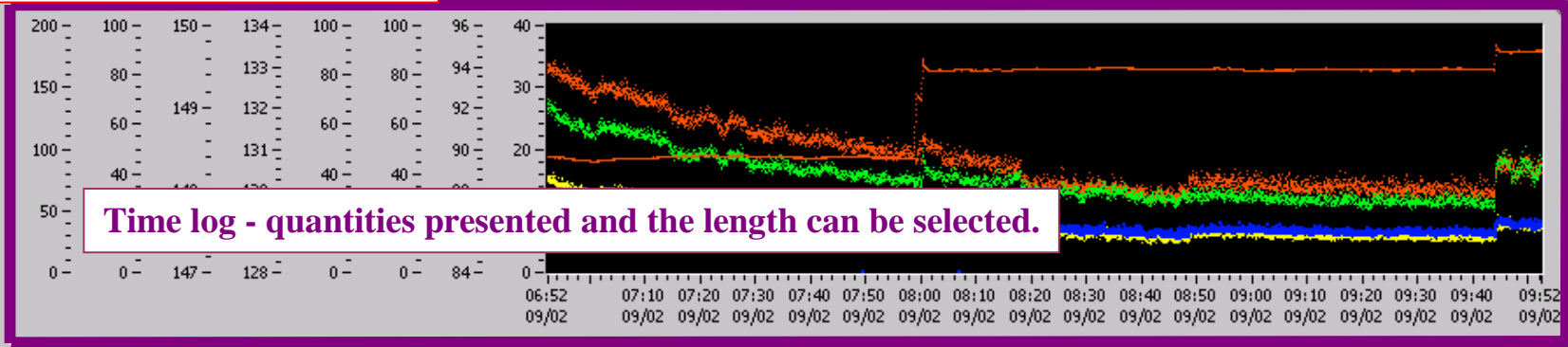
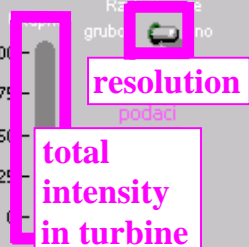
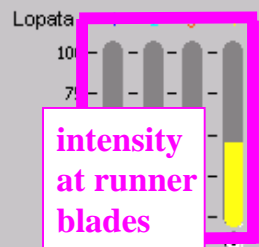
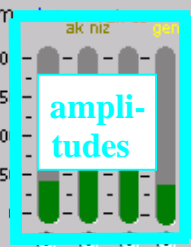
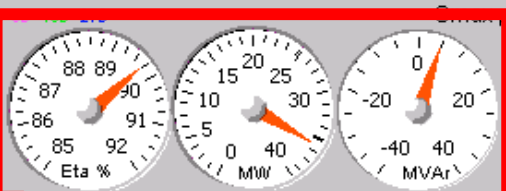
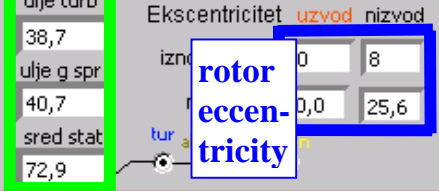
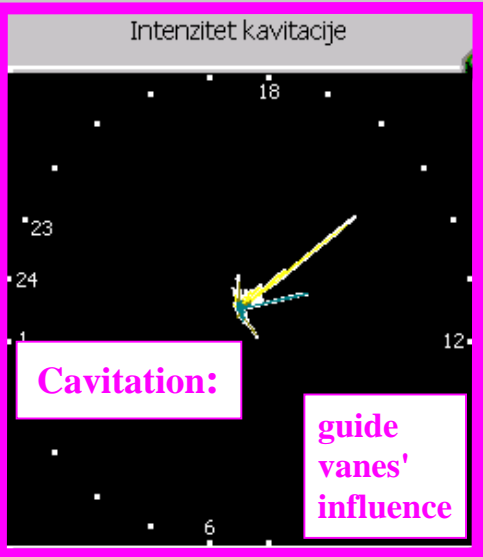
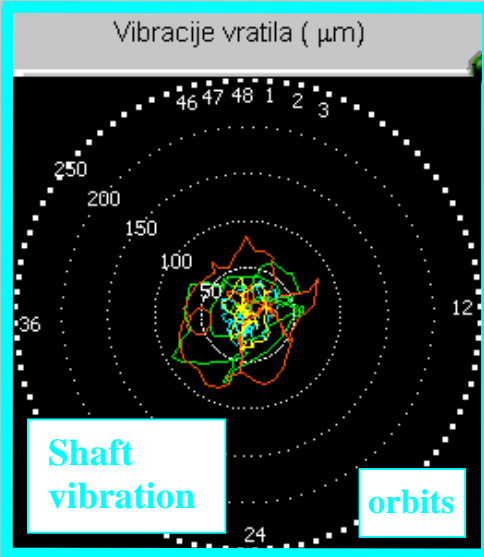
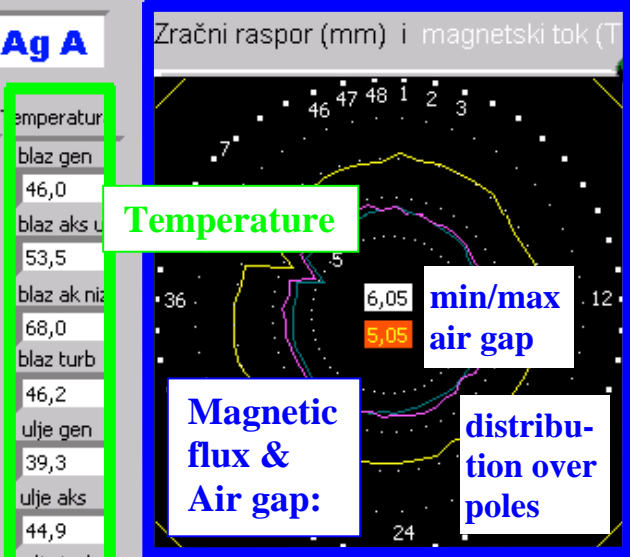
200	100	150	134	100	100	96	40
150	80	149	133	80	80	94	30
100	60	132	131	60	60	92	20
50	0	147	128	0	0	84	0

English or a local language is used; here, the language is Croatian.



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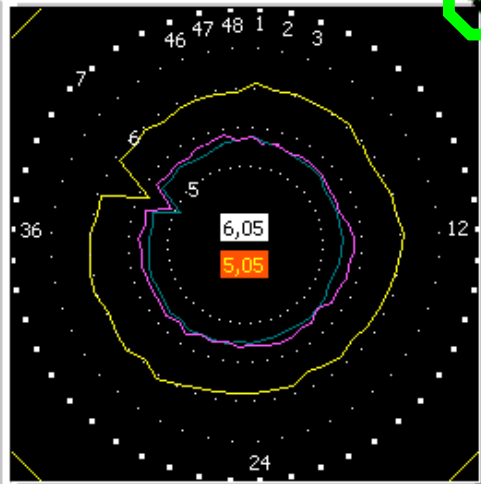
Režim	temperatur
GVS m	blaz gen
149,25	46,0
DVS m	blaz aks U
129,65	53,5
Pad ul r n	blaz ak niz
0,36	68,0
OPK %	blaz turb
70,4	46,2
ORK %	ulje gen
69,6	39,3
Qag m3/s	ulje aks
198,3	44,9
Srad MW	ulje turb
35,9	38,7
Sjal MVA	ulje g spr
4,7	40,7
Eta %	sred stat
89,7	72,9
SradD M	
0,5	
SjaD MVA	
-0,8	
QagD m3	
0,9	



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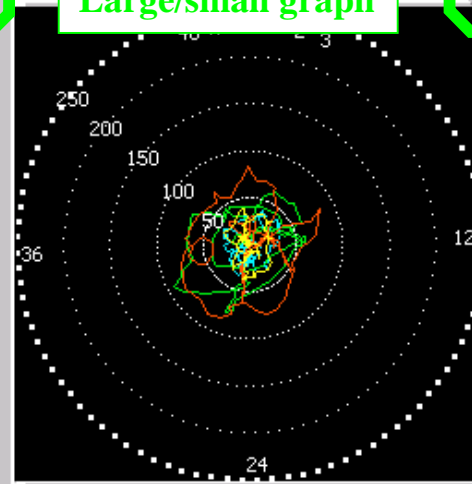
Režim	Temperatura
GVS m	blaz gen
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DVS m	blaz aks uz
129,65	53,5
Pad ul r m	blaz ak niz
0,36	68,0
OPK %	blaz turb
70,4	46,2
ORK %	ulje gen
69,6	39,3
Qag m3/s	ulje aks
198,3	44,9
Srad MW	ulje turb
35,9	38,7
Sjal MVar	ulje g spr
4,7	40,7
Eta %	sred stat
89,7	72,9
SradD MW	
0,5	
SjaD MVar	
-0,8	
QagD m3/s	
0,9	

Zračni raspored (mm) i magnetski tok

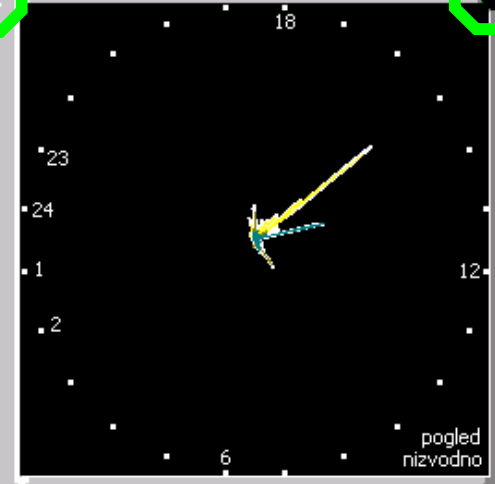


Large/small graph

Vibracije vratila (µm)

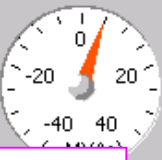
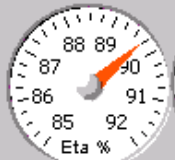


Intenzitet kavitacije

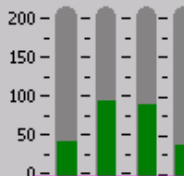


Ekscentricitet uzvod nizvod 0 90 180 270

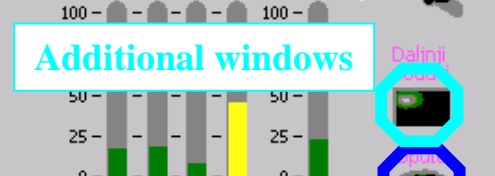
iznos (µm): 0 8
na polu: 0,0 25,6



Smax µm tur ak niz ak uz gen



Lopata 1 2 3 4 Ukupno Razlučivanje grubo fino



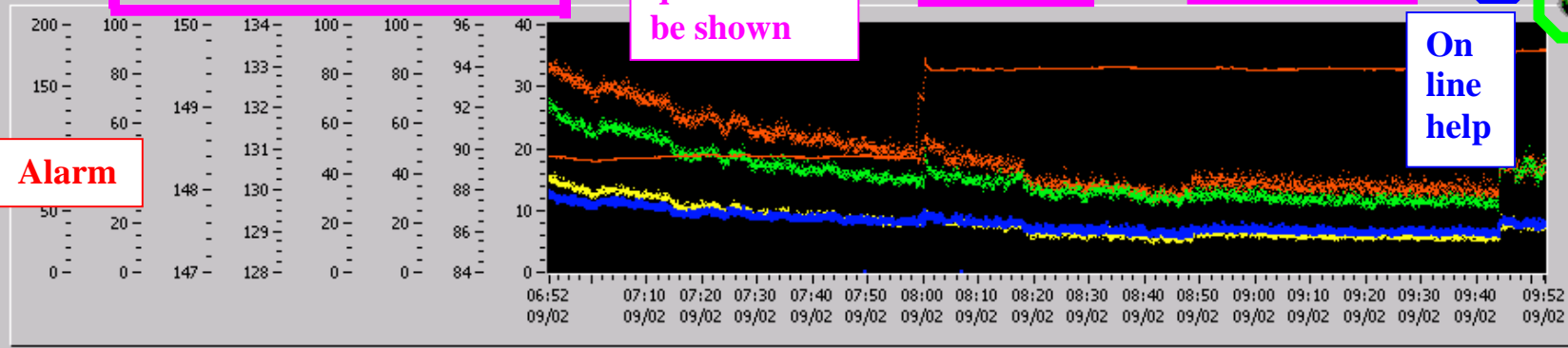
Additional windows

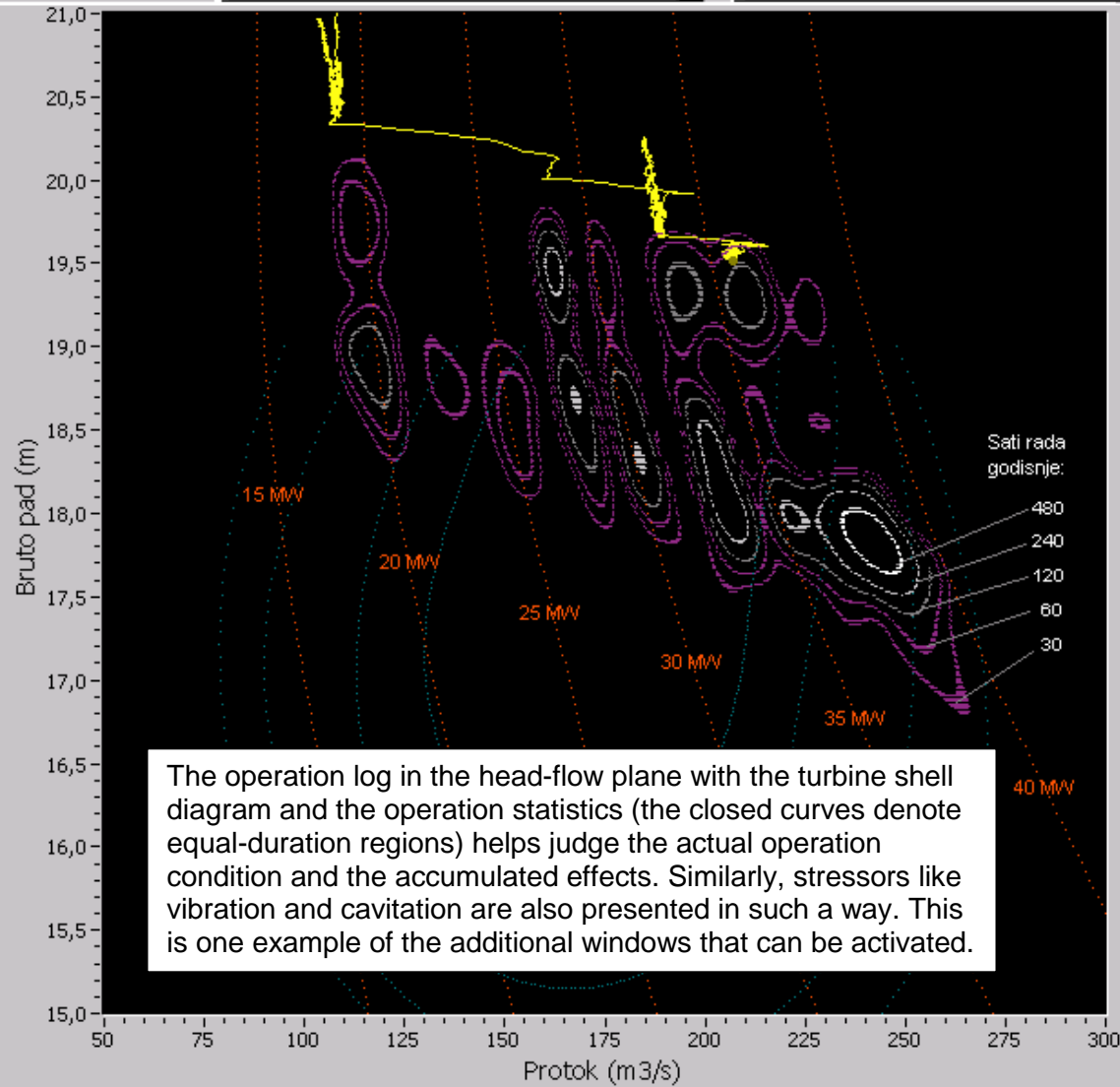
Selection of quantities to be shown

Selection of quantities to be shown

On line help

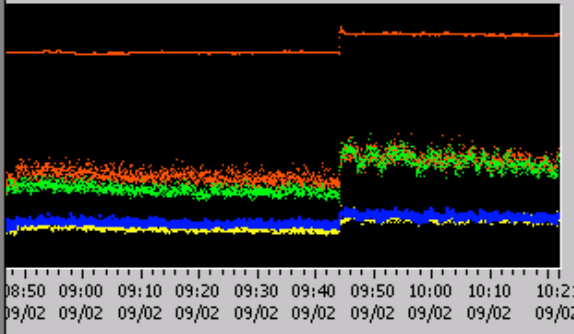
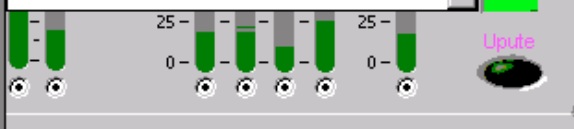
Alarm





The operation log in the head-flow plane with the turbine shell diagram and the operation statistics (the closed curves denote equal-duration regions) helps judge the actual operation condition and the accumulated effects. Similarly, stressors like vibration and cavitation are also presented in such a way. This is one example of the additional windows that can be activated.

- DALJNI PODACI
- Vibracije vratila - pregled
 - Vibracije vratila nad parametrima rezima
 - Zracni raspor iznad pola detaljno
 - Zracni raspor iznad pola nad vremenom
 - Oblik rotora i statora
 - Gibanje osi rotora
 - Radijalno rastezanje polnog kotaca
 - Radijala stabilnost spoja vratila i polnog kotaca
 - Magnetski tok nad vremenom
 - Magnetska karakteristika polova
 - Njihanje snage nad parametrima rezima
 - Njihanje snage nad vremenom
 - Kavitacija - intenzitet nad parametrima rezima
 - Temperature
 - Radna točka**
 - Pregled signala- valni oblici
 - Pregled signala - spektri



12

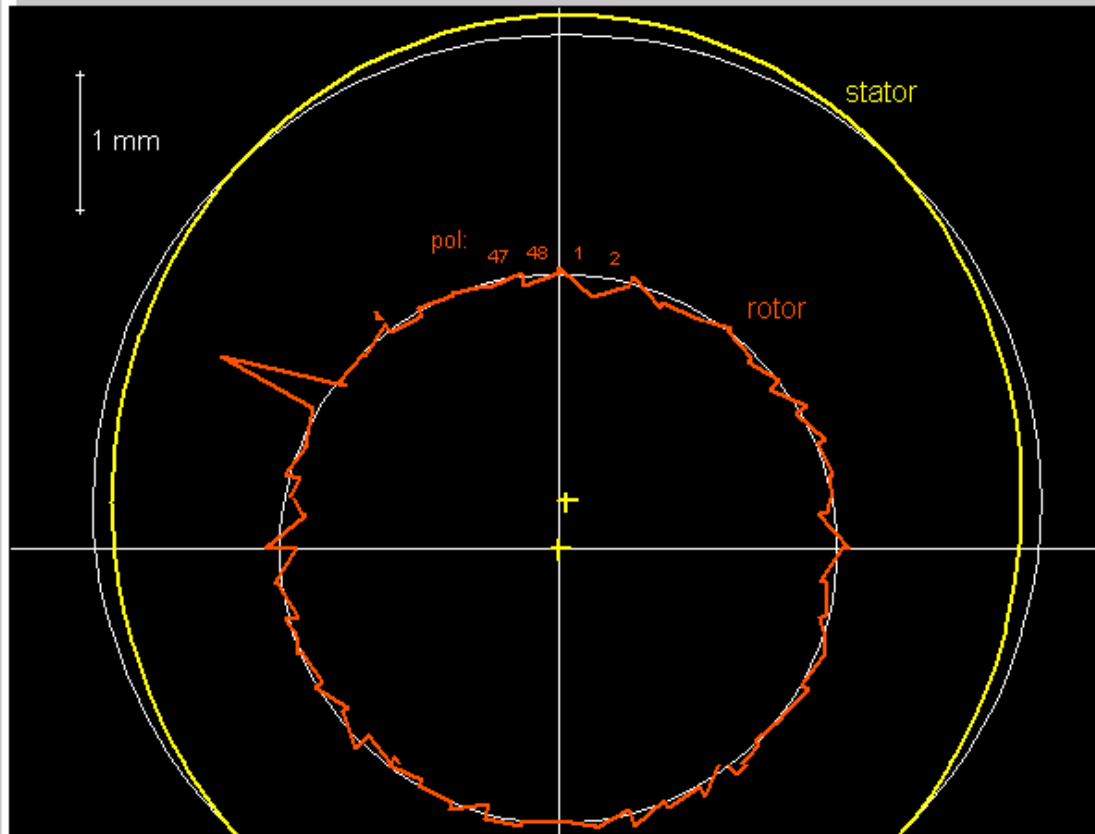
pogled nizvodno

azlučivanje

o fino

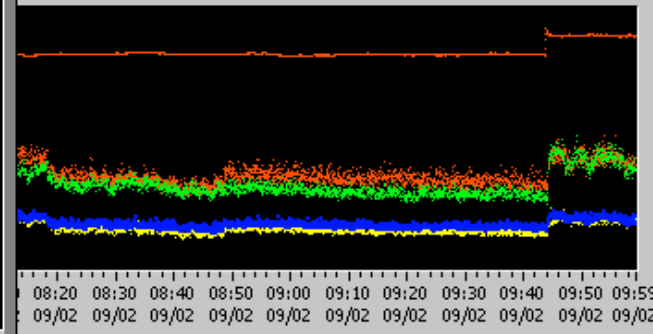
Daljni podaci

Upute



The stator's and rotor's forms deduced from the air gap data, together with this data itself attached on the rotor form. The deviation from the ideal forms (white) and the air gap data are all in scale. Instead of describing the air gap over a pole by its mean value, a linear approximation of its form along the circumference is shown. Note that, in the present case, one pole stands out by 1 mm into the air gap.

- DALJNI PODACI
- Vibracije vratila - pregled
 - Vibracije vratila nad parametrima rezima
 - Zracni raspor iznad pola detaljno
 - Zracni raspor iznad pola nad vremenom
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 - Temperature
 - Radna tocka
 - Pregled signala- valni oblici
 - Pregled signala - spektri



12

pogled nizvodno

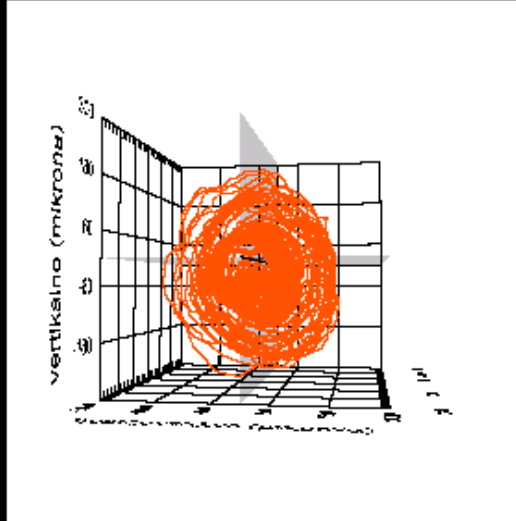
azlučivanje

o fino

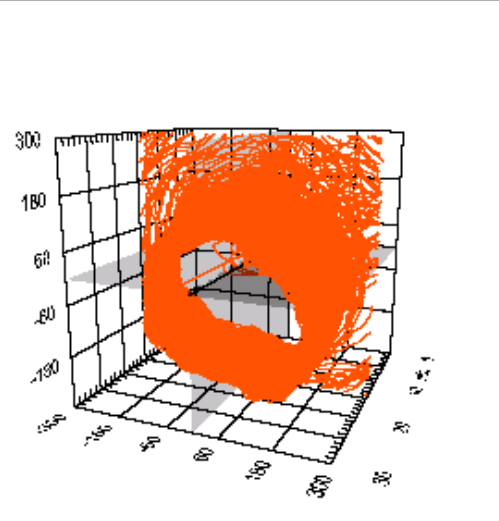
Daljni podaci

Upute

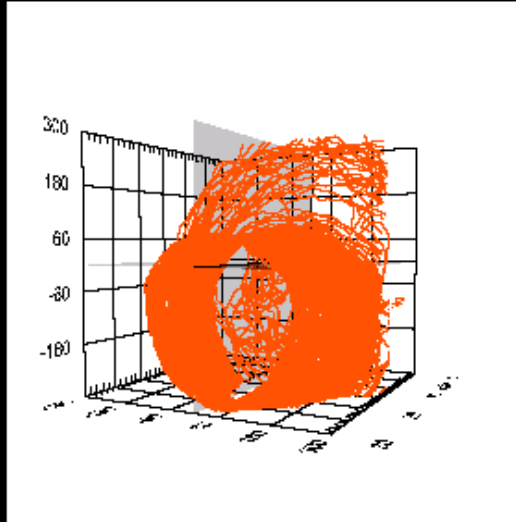
Tekuci položaj osi rotora uz generatorski lezaj



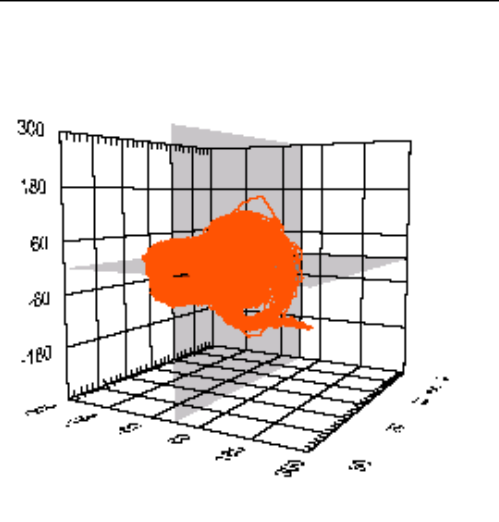
... uz aksijalni lezaj, uzvodno



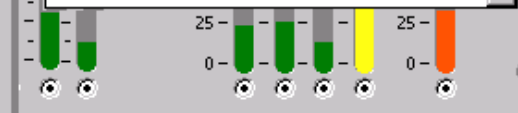
... uz aksijalni lezaj, nizvodno



... uz turbinski lezaj



- DALJNI PODACI
- Vibracije vratila - pregled
 - Vibracije vratila nad parametrima rezima
 - Zracni raspor iznad pola detaljno
 - Zracni raspor iznad pola nad vremenom
 - Oblik rotora i statora
 - Gibanje osi rotora**
 - Radijalno rastezanje polnog kotaca
 - Radijalna stabilnost spoja vratila i polnog kotaca
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 - Magnetska karakteristika polova
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 - Njihanje snage nad vremenom
 - Kavitacija - intenzitet nad parametrima rezima
 - Temperature
 - Radna tocka
 - Pregled signala- valni oblici
 - Pregled signala - spektri



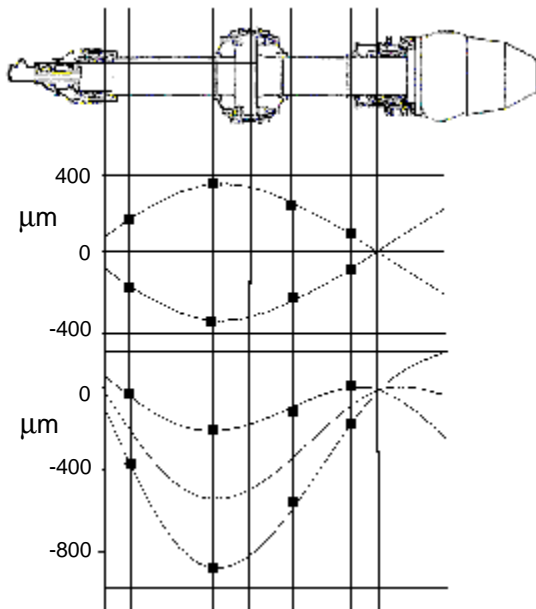
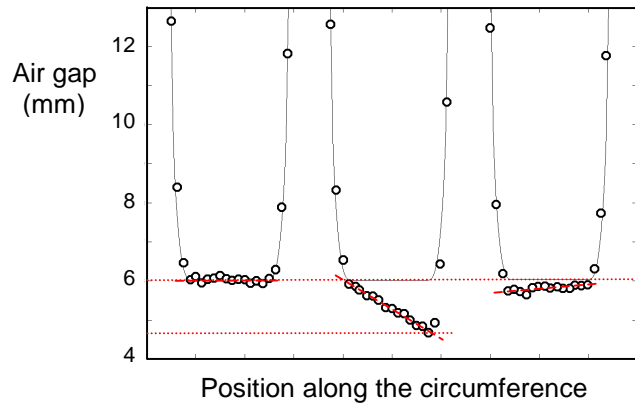
The shaft axis kinematics followed at four locations along the axis is a good way to assess the rotor movement. It also tells much about the issues like the lubrication situation in the bearings.

40 16:50 17:00 17:10 17:20 17:30 17:40 17:50 18:00 18:10 18:20
02 07/02 07/02 07/02 07/02 07/02 07/02 07/02 07/02 07/02 07/02

Application examples

Pole-shape identification

A detailed survey of the air gap variation along the pole's circumferential length, shown in figure, yields details on the pole finish and its mounting. Here, three neighboring poles are compared to the ideal shape. One pole stands out strongly and is inclined.

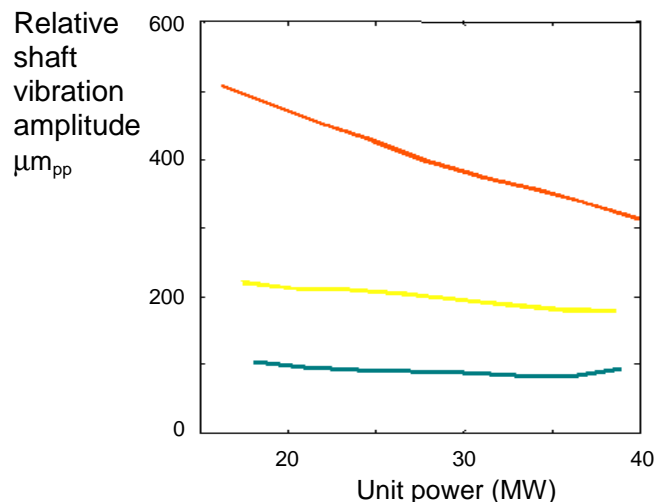


Vibration modeling

An elastic-beam model drawn through the *relative shaft vibration amplitude* data as sensed along the shaft describes well the true form of the vibration distribution in the horizontal plane (upper graph) and the vertical plane (lower graph). Adding to this few plausible assumptions, one gets a tool that predicts machinery loading and describes circumstances in the bearings, which are otherwise hard to assess. Further, the model reduces data needed to describe vibration and makes that description robust.

Vibration reduction

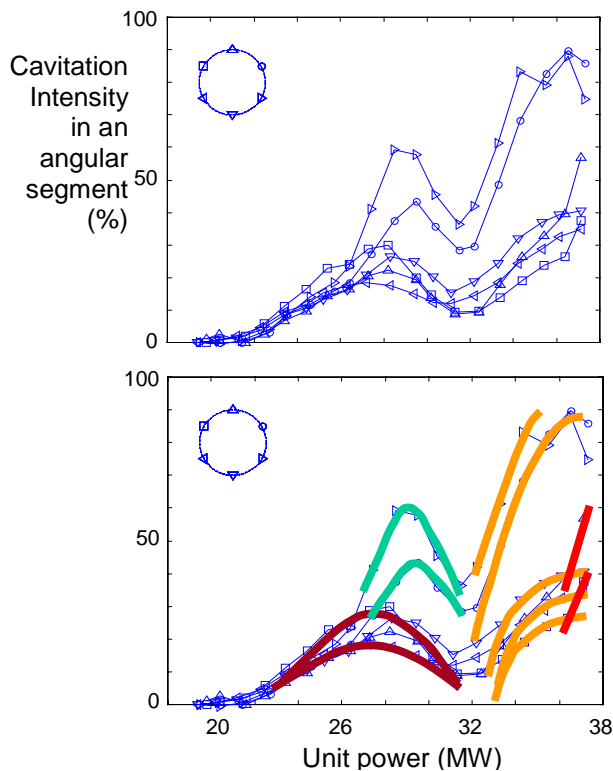
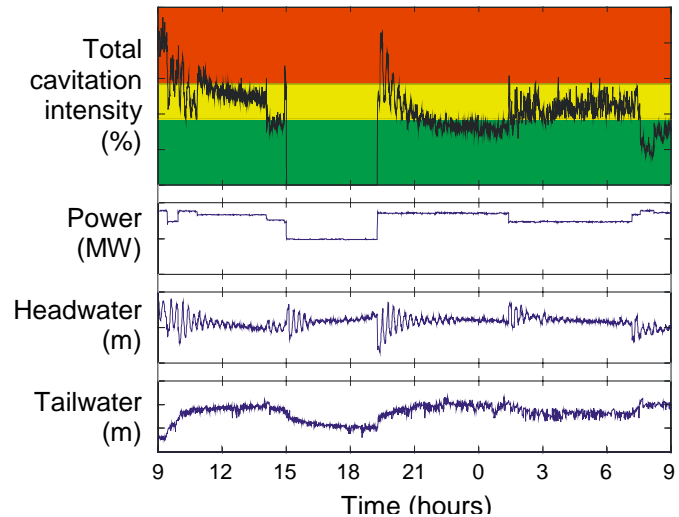
A unit suffered from severe shaft vibration. Magnetic flux data revealed the cause, and air gap data yielded a detailed description of shaft kinematics. This facilitated an efficient two-step counter-measure which suppressed the vibration amplitude by a factor 3-5 from **Initial** to **Centered** and then to **Counter-Centered** [6].



Cavitation monitoring

The multidimensional algorithm, based on 4-8 sensors per unit, yields:

- a reliable and true estimate of the total cavitation intensity (right),
 - intensity of cavitation at a runner blade,
 - data on the guide vanes' influence.
- All this comes
- with or without spatial resolution, and
 - with or without resolution over cavitation mechanisms (different types of cavitation or cavitation in different locations).



Spatial resolution

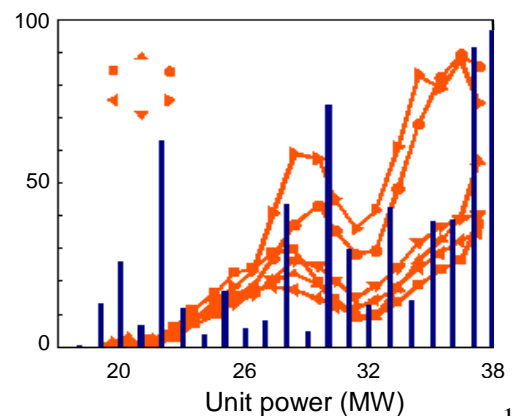
In a large-diameter bulb unit monitored, cavitation was strongly varying in the vertical plane. This was quantified by the analysis resolving angular segments of the flow. A shift of the intensity maximum in the rotation direction (clockwise) is observed.

Cavitation mechanisms

Almost regularly, one finds several cavitation processes in a turbine; there are 4 in the example shown. It is necessary to distinguish between them, since - depending on the aim of monitoring - not all are important (e.g., not all are erosive).

Operation optimization

Combining the results like those illustrated above (red) with the statistics of head, tailwater, and power values (blue), one can optimize unit operation for a minimum accumulated cavitation erosion (which is also monitored).



Turbine instability

Cavitation monitoring resolving angular segments in a turbine and yielding data on each runner blade independently was used, in a case illustrated here, in two operational situations:

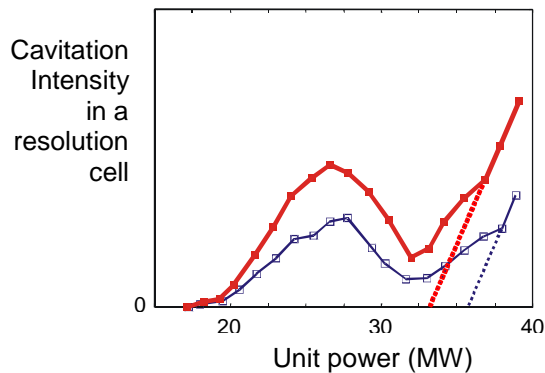
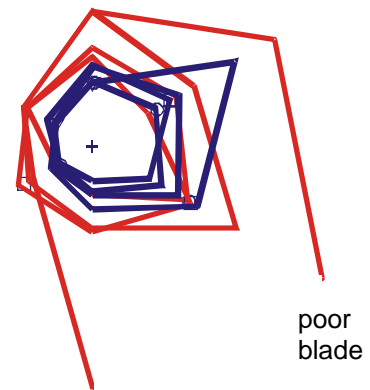
blue - normal;

red - with trash caught on guide vanes.

Radial co-ordinate - cavitation intensity;

angular co-ordinate - position of a segment.

The four curves in each color, corresponding to four blades, show that, when the trash is acting, one poor blade cavitates explosively within a portion of a revolution. This was recognized as the cause of strong once-per-revolution power fluctuations the unit suffers from.



Malfunction detection

In order to test the sensitivity of a monitor's cavitation channel to changes in turbine's behavior or deterioration effects, one guide vane was slightly shifted from its normal position. In the related spatial resolution cell of monitor's output, strong change was found -

blue - normal vane position,

red - shifted:

cavitation was intensified and its threshold shifted towards lower loading. At the same

time, there was no recognizable change in the output showing the total intensity of cavitation in the turbine. This illustrates another quality of the multidimensional monitor. By involving resolution in important variables, it ensures extremely high sensitivity in the detection of the deterioration effects.

Conclusion

This paper describes a simple multidimensional monitor which provides a cost-effective alternative to large and expensive systems for monitoring hydropower units. Implementation of the monitor is preceded by a diagnostic test, and the monitor is based on a multi-dimensional algorithm.

The multidimensional cavitation monitor, implemented independently or as a part of a general monitoring system, distinguishes between turbine parts and between cavitation mechanisms; it yields detailed data on cavitation, useful for diagnostics and operation optimization; and it detects changes and deterioration effects with a high sensitivity.

References

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